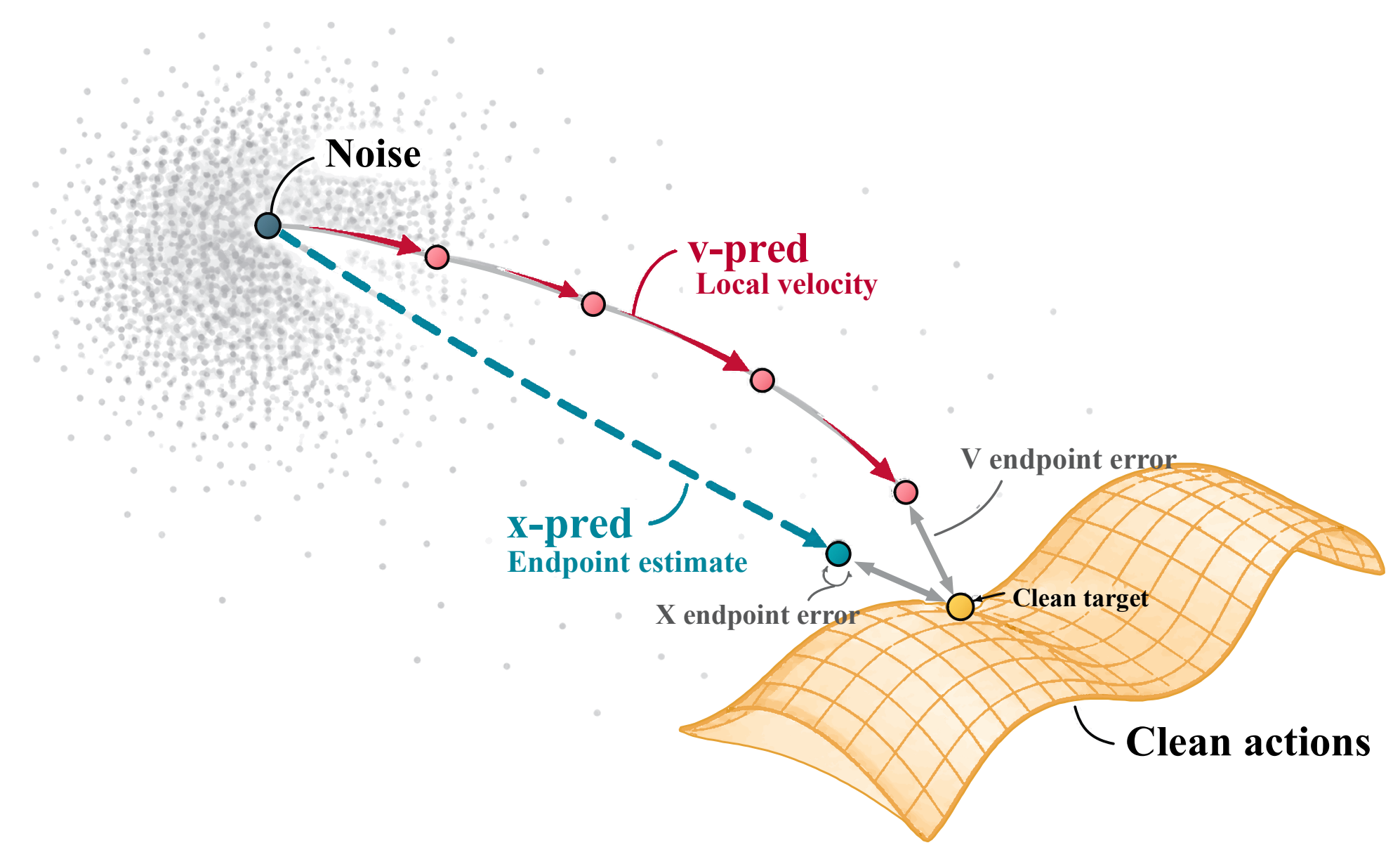

Noise
v-pred
Local velocity
x-pred
Endpoint estimate
V endpoint error
X endpoint error
Clean target
Clean actions